# PCW Hardware 

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March 6, 2024


#### Abstract

This document describes what I have found out about the hardware of the Amstrad PCW, in the course of writing JOYCE. Some of this has been deduced by me; a lot has come from other sources.


## Contents

1 General principles ..... 5
2 Boot ROM ..... 5
3 RAM and paging ..... 5
3.1 PCW ("extended") paging mode ..... 5
3.2 CPC ("standard") paging mode ..... 6
4 The screen ..... 6
4.1 I/O ports ..... 6
4.2 The Roller-RAM ..... 7
5 Interrupts ..... 7
5.1 Timer interrupts ..... 8
5.2 Floppy controller interrupts ..... 8
5.3 Serial port interrupts ..... 8
5.4 Daisywheel interrupts ..... 8
6 Printer ports ..... 8
6.1 PCW8256/8512/9256/10 printer controller ..... 8
6.1.1 I/O ports ..... 8
6.1.2 Printer commands ..... 9
6.1.3 Example command sequences ..... 10
6.1.4 PCW matrix printer fonts ..... 10
6.2 PCW9512 printer controller ..... 11
6.3 PCW9512 PAR port ..... 12
6.4 CPS8256 CEN port ..... 13
6.5 Standalone CEN port ..... 13
7 Communications interfaces ..... 13
7.1 CPS8256 ..... 13
7.1.1 Z80-DART registers ..... 14
7.1.2 CPS8256 Centronics port ..... 15
7.1.3 CPS8256 Serial port ..... 15
7.2 SCA Mark 2 Interface ..... 15
7.3 LocoLink interface ..... 16
7.4 PCW Linkit ..... 17
7.5 PCWMail ..... 17
7.6 Prototype serial interface ..... 17
8 Floppy drives ..... 17
8.1 The floppy controller and other ports ..... 18
8.2 Floppy drive support ..... 18
8.3 Floppy controller probe ..... 18
8.3.1 Detect floppy controller type ..... 18
8.3.2 Detect drive type ..... 18
9 Hard drives ..... 19
9.1 Cirtech Gem ..... 19
9.1.1 Cirtech Gem (ATA) ..... 20
9.1.2 Cirtech Insyder / Hardpak ..... 20
9.2 Cirtech Flash Drive ..... 20
9.3 ASD PCWHD10 / PCWHD20 ..... 21
9.4 Timatic Winchester Expansion Box ..... 21
9.5 Other hard drives ..... 22
10 Keyboard ..... 22
10.1 Keyboard matrix ..... 23
10.2 Keyboard Links ..... 24
10.3 Keyboard Joystick(s) ..... 24
10.4 Physical connection ..... 25
10.4.1 Wire protocol ..... 25
11 Pointing Devices ..... 25
11.1 AMX Mouse ..... 25
11.2 Kempston Mouse ..... 26
11.3 Keymouse ..... 26
11.4 Electric Studio light pen ..... 26
12 Joysticks ..... 27
12.1 Keyboard joystick(s) ..... 27
12.2 Kempston interface ..... 27
12.3 Spectravideo interface ..... 28
12.4 Cascade (JoyceStick) interface ..... 28
12.5 DKTronics interface ..... 28
13 Sound Generators ..... 29
13.1 DKTronics sound generator ..... 29
14 Networking ..... 29
14.1 Multilink ..... 29
14.2 Amstrel ..... 30
15 Scanners / Image Capture ..... 30
15.1 MasterScan ..... 30
15.2 ProScan ..... 30
15.3 Digitisers ..... 30
A Dot matrix printer fonts ..... 31
A. 1 The character width table. ..... 31
A. 2 The NLQ font ..... 31
A. 3 The draft font ..... 32
A. 4 Some worked examples ..... 32
A.4.1 NLQ: Character 0 (à) using BIOS 1.15 ..... 32
A.4.2 Draft: Character 0 (à) using BIOS 1.15 ..... 34
A.4.3 Repetition of columns: Character 62 (' $=$ ') using BIOS 1.4 ..... 34
A. 5 Matrix fonts in LocoScript 1.00-1.20 ..... 35
A.5.1 PS widths table ..... 35
A.5.2 NLQ font ..... 35
A.5.3 Draft font ..... 35
A.5.4 Z80 code ..... 36
A. 6 Matrix fonts in LocoScript v1.31 ..... 36
A. 7 Matrix fonts in LocoScript v1.40-1.50 ..... 36
A. 8 Matrix fonts in LocoScript 2-4 ..... 37
B The LocoLink wire protocol ..... 40
B. 1 Basic concepts ..... 41
B.1.1 Bit mapping at the PC end ..... 41
B. 2 Link idle ..... 41
B. 3 Sending ..... 41
B.3.1 Sending a byte ..... 41
B.3.2 Sending a packet ..... 41
B. 4 Receiving ..... 42
B.4.1 Receiving a byte ..... 42
B.4.2 Receiving a packet ..... 42
B. 5 Example ..... 43
B. 6 Serial connection ..... 43
B. 7 Startup sequence ..... 43
B. 8 While the link is running ..... 44
B.8.1 LocoLink v1.03 / v1.04 ..... 44
B.8.2 LocoLink v2.02 ..... 45
B.8.3 LocoLink for Windows / LocoLink 16 ..... 47
B. 9 Emulated DOS filesystems ..... 50
C The Gem Drive System Track ..... 50
C. 1 The boot programs table ..... 51
C. 2 The HDRIVER.FID image ..... 52
C. 3 The splash screen ..... 52
C. 4 HDRIVER.FIC image ..... 52
D The Flash Drive System Track ..... 52
E The Timatic Winchester Expansion Box Partition Table ..... 53

## 1 General principles

The PCW's I/O is (for the most part) conducted using the Z80's IN and OUT instructions, rather than memory-mapped I/O. In nearly all cases, only the bottom 8 bits of the port number are decoded, and so ports are specified with 2-digit identifiers (eg: port F0h, not port 00F0h).

## 2 Boot ROM

Most of this information is derived from Jacob Nevins' description of the boot process (with disassembly) at [http://www.chiark.greenend.org.uk/~jacobn/cpm/pcwboot.html](http://www.chiark.greenend.org.uk/~jacobn/cpm/pcwboot.html).

The PCW has no separate boot ROM. Instead, on startup, instruction fetches return a stream of bytes irrespective of address. This stream is 778 bytes long, and generates a 256 -byte boot program at the start of memory (addresses 0002h-0101h). The last two bytes of the instruction stream (D3 F8) write 0 ('end of boot sequence') to port 0 F 8 h . The next instruction fetch will then be from address 0002 h , the start of the boot program.

There are two known boot programs; one for dot-matrix PCWs, and one for daisywheel PCWs. They are identical except for two bytes: the code used to check if the boot sector is valid, and another byte which has presumably been altered so the checksum comes out the same.

## 3 RAM and paging

The PCW memory is divided into blocks of 16k. A PCW8256 has 16 blocks, while a fully-upgraded 2 Mb PCW has 128 . The processor can only address 64 k at a time; the I/O ports F0h-F3h are used to select which blocks it sees where.

F0h controls what the processor sees at 0000h-3FFFh.
F1h controls what the processor sees at 4000h-7FFFh.
F2h controls what the processor sees at 8000h-BFFFh.
F3h controls what the processor sees at C000h-FFFFh.

### 3.1 PCW ("extended") paging mode

Usually, values written to the memory management ports have bit 7 set and the other 7 bits set to the block number:

| Bits |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 1 | block number |  |  |  |  |  |  |

- for example, block 4 could be selected into memory at 8000 h by an OUT ( 0 F 2 h ), 84 h . If the block number is out of range then the top bits will be ignored - so attempting to select block 24 on a 256 k computer would actually select block 8 .


### 3.2 CPC ("standard") paging mode

This paging mode is not used by any CP/M or LocoScript software except perhaps the memory tester (RAMTEST.COM). It is present because the PCW was based on a never-built design for $\mathrm{ANT}^{1}$, a successor to the CPC range.

If CPC paging mode is used, then two blocks can be in one slot at once; memory writes go to one, and reads to the other.

| Bits |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0 | block to read |  |  |  |  |  |  |
| unused | block to write |  |  |  |  |  |  |

This method only allows access to the first 128k of memory, which is another good reason why no PCW programs use it.

There is an additional port used in CPC paging: port F4h (output). The value written to this is interpreted as follows:

| Bits |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 |  |  |
| lock C000..FFFF | lock 8000..BFFF | lock 4000..7FFF | lock 0..3FFF | unused |  |  |  |  |

If a memory range is set as "locked", then the "block to read" bits are ignored; memory is read from the "block to write".

## 4 The screen

The screen is a $720 \times 256$ array of pixels, each pixel twice as high as it is wide. The video controller can fetch the screen data from anywhere in the bottom 128k of RAM - see port F5h below.

### 4.1 I/O ports

The following ports are used by the video controller:
F5h (output) sets the address of the "Roller-RAM" within the bottom 128k of memory. The "Roller-RAM" is a 512-byte table whose format is given in section 4.2. The value written to this port can be interpreted as follows:

| Bits |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| block |  |  |  |  |  |  |  |
| offset $/ 512$ |  |  |  |  |  |  |  |

- e.g, to move the Roller-RAM to offset 3200 h in memory block 4, write the value 10011001 binary (99h) to port F5h.

[^0]F6h (output) sets the vertical origin of the screen. The value written to it specifies which line of the Roller-RAM corresponds to the top line of the screen. So OUT 0 F6h, 8 means that the video controller will display pixel line 8 at the top of the screen - essentially, scrolling up by 8 pixels.

F7h (output) Bits 6 and 7 of this port are used. If bit 7 is set, then the screen will display in inverse video (black on green/white). If bit 6 is set, then the screen is displayed; otherwise it will be blank.

F8h (output) This port is used for various purposes, but the two which are videorelated are:

OUT F8h, 8 Disable the video controller. External hardware (a TV modulator?) must drive the screen.

OUT F8h, 7 Enable the video controller.
F8h (input) The bits that concern the video controller here are:
bit 6 Frame flyback; this is set while the screen is not being drawn.
bit 460 Hz PCW; only the top 200 lines of the screen will be visible.

### 4.2 The Roller-RAM

The Roller-RAM is treated as an array of 256 little-endian words. Each word is a coded pointer to the screen bitmap for this line, formed:

| Bits |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| block |  |  | offset / 16 |  |  |  |  |  |  |  |  |  | offset |  |  |

The top 3 bits give the memory block number. Bits $0-12$ give the offset of the line within the block. However, it would take 14 bits to span a 16 k block, and there are only 13 left. So to convert bits $0-12$ into the address of a screen line, you have to use a formula such as

```
address = (offset & 7) + 2 * (offset & 0x1FF8) ;
```

Once you have the address of a screen line, it consists of 90 bytes, at intervals 8 apart (so a line would be stored in bytes $0,8,16,24,32 \ldots$...). This allows 8 lines to be interleaved for ease of printing text.

## 5 Interrupts

Various peripherals can generate interrupts. When checking the source of an interrupt, PCW CP/M checks in the order FDC, timer, other peripherals.

### 5.1 Timer interrupts

The timer interrupts 300 times a second. It also increments a counter which can be read from the bottom 4 bits of port F4h. The counter goes from 0-15, and stays at 15 having got there. Reading the counter resets it.

This allows PCW system software to compensate for missed timer interrupts. On interrupt, it reads the counter, and if it is more than 1 then it knows some interrupts have been missed. If it is 0 , then the timer did not interrupt; the interrupt must be from a different source.

### 5.2 Floppy controller interrupts

The floppy controller can be programmed to send a normal interrupt or a non-maskable interrupt (NMI) on completing a command. See Section 8.1.

If the floppy controller has tried to interrupt (regardless of whether it is set to produce an NMI, a normal interrupt, or nothing at all) then bit 5 of the value read from port F 8 h will be 1 . Otherwise it will be 0 .

### 5.3 Serial port interrupts

The CPS8256 interface (see section 7.1) can be programmed to generate interrupts.

### 5.4 Daisywheel interrupts

The daisywheel printer (see section 6.2) can be programmed to interrupt when it has finished a command.

## 6 Printer ports

### 6.1 PCW8256/8512/9256/10 printer controller

### 6.1.1 I/O ports

The PCW uses two I/O ports to communicate with the printer controller - ports 0 FCh and 0 FDh .0 FCh appears to be used to initialise the controller, while 0 FDh controls the printer itself.

FCh (input) returns a controller error number. The PCW XBIOS only reads this when the controller reports an error (see bit 0 of port FDh). Values that can be returned are:

0 Underrun
1 Printer RAM fault
3 Bad command
5 Print error
0F8h Normal operation (no error).
If this port returns any other value, then "No printer" is displayed as an error.

FCh (output) is used to send commands to the printer controller. Each command is a multiple of 2 bytes long. The meaning of the commands sent to ports FCh and FDh appears to be the same, but commands are only written to port FCh while the printer is being reset.

FDh (input) returns the status of the printer. The meanings of the bits are as follows:

| Bit | Meaning |
| :---: | :---: |
| 7 | Bail bar - 1 if it's in, 0 if out |
| 6 | If 0, printer is executing command. If 1, printer has finished. |
| 5 | Always 0 (for daisywheel PCWs, it's 1 when the PCW is booted, <br> so this bit can be used to test the printer type). |
| 4 | 0 if print head is at left margin; else 1. |
| 3 | Sheet feeder present? |
| 2 | Paper sensor -1 if paper is present, else 0. |
| 1 | If 0, ready - commands can be sent to port FDh. If 1, busy - they can't. |
| 0 | If 1, controller fault - see IN 0FCh. |

FDh (output) is used to send commands to the printer. All printer commands are sent to this port except during a reset.

### 6.1.2 Printer commands

Printer commands are a multiple of 2 bytes long. Commands which are longer than two bytes end with the two bytes $\mathrm{C} 0,00$. Parameters use a vertical resolution of $\frac{1}{360} \mathrm{in}$; the horizontal resolution depends on the speed the motor is running at, but is either $\frac{1}{720}$ in or $\frac{1}{1440} \mathrm{in}$. In the following descriptions, the unit of horizontal measure is called the "tick".
$\mathbf{0 0 , 0 0}$ First initialisation command sent to port 0 FCh during boot up; possibly does a self-test.

A4,nn Line feed by $\frac{n n}{360}$ inches. Used only for feeds of $\frac{1}{30}$ in and less (ie, $n<=12$ ). Not followed by a $\mathrm{C} 0,00$ command.
$\mathbf{A 8 , n n} ; \mathbf{A 9}, \mathbf{n n} ; \mathbf{A A}, \mathbf{n n} ; \mathbf{A B}, \mathbf{n n}$ Move the print head and print a line. Bits 0 and 1 of the command byte give the print head speed and direction:
bit 0 If set, print head moves to the right; else left.
bit 1 If set, print head moves at half speed. If not, full speed.
The second byte of the command says by how many ticks the head should move in the direction of travel before the first output is printed. The PCW matrix driver assumes that the head will actually move by 9 fewer ticks; this may be because the motor can't start instantly.
This command is then followed by a number of data commands. These are of two kinds - to print, or to move the head by a specified number of ticks.
The command to print a column is treated as a 16-bit big-endian word with the following bitfields:

- Bits 15-12 are 0 .
- Bits 11-9 give the column spacing. 0 is 5 ticks, 1 is 6 ticks, ..., 7 is 12 ticks.
- Bits $8-0$ are 1 to fire the pins. Bit 8 is the bottom pin, bit 0 is the top.

The other type of command moves the head. These are normally at the end (to put the print head in the right place for the next row). The bit pattern for this type of command is:

- Bits 15-13 are 1,0,0 (so this command is between 80 h and 9 Fh ).
- Bits 12-0 are the number. If the low 8 bits are 0 , add 256 . This means the commands, in increasing numerical order, are: $80,0180,02 \ldots 80, \mathrm{FF}$, $80,00,81,01$ etc.

Finally, the command ends:
$\mathbf{C 0 , 0 0}$ End of command. This moves the head a further 11 ticks in the direction of travel, because the motor can't stop instantly either.

AC,nn Line feed by $\frac{n}{360}$ inches. If nn is 0 , feed $\frac{256}{360}$ inches. To feed more than that, pass further commands where bits 15-13 are 1,0,0 and bits 12-0 are the encoded number to feed - eg: AC,30 92,00 C0,00

This command is also terminated by a $\mathrm{C} 0,00$ end sequence.
B8,00 Reset printer. Moves the print head to the left margin.
$\mathbf{C 0 , 0 0}$ end of command sequence.

### 6.1.3 Example command sequences

- 00,00 A4,01 \{ A9,C0 \} B8,00 - sent to port 0FCh as initialisation sequence. The A9,C0 pair is sent if the print head is against the left margin after the initial reset; this ensures that wherever the head was, its ability to move has been tested.
- $\mathrm{C} 0,00 \mathrm{~B} 8,00-$ sent to port 0 FCh as printer reset sequence.
- AC,3D C0,00 - line feed at 6 lines/inch
- AB, 86,0E,data,0E,data,...,0E,data, 02,00, ... (21 times) ..., 80, 04, C0,00 - print a line of graphics in the ESC L graphics mode. The AB, 86 starts printing and moves the head 134-9=125 ticks to the right. The commands starting 0 E are the graphics columns, spaced 12 ticks apart. The 2102,00 commands and the 80,04 move the head 130 ticks to the right of the last column, and the $\mathrm{C} 0,00$ moves it a further 11 ticks. Combined with the lead-in on the next line, this leaves the head ready to print under the first unprinted column of this line.


### 6.1.4 PCW matrix printer fonts

Although it is not strictly part of the hardware specification, the memory layout used by the dot-matrix printer fonts under $\mathrm{CP} / \mathrm{M}$ and LocoScript 1 is described in Appendix A.

### 6.2 PCW9512 printer controller

Unlike most of the other ports, the 9512 printer controller decodes its I/O address as more than just 8 bits, and is thus accessed at $\mathrm{I} / \mathrm{O}$ addresses $00 \mathrm{FCh}, 01 \mathrm{FCh}$ and 00 FDh .

The bits returned by IN ( 0 FDh ) are:

| Bit | Meaning |
| :---: | :---: |
| 7 | 1 if the printer can accept commands <br> 0 if commands can't be sent to it |
| 6 | Usually 0. The interrupt handler checks this bit,. <br> but the significance of it is unclear. |
| 5 | 1 if the printer is idle, 0 if it's executing a command. <br> On dot-matrix PCWs, this bit is always 0. |
| 4 | Always seems to be 1 |
| 3 | Unknown |
| 2 | 1 if the printer has caused an interrupt. |
| 1 | 0 if bytes can be sent to the controller, else 1. |
| 0 | 1 if bytes can be read from the controller, else 0. |

The controller is accessed by sending two-byte commands. The first byte specifies the command, and the second contains any required data. To send a command:

1. Wait until IN ( 00 FDh ) bit 1 is zero.
2. OUT (01FCh),command_byte
3. OUT $(00 \mathrm{FCh})$,data_byte

If the command returns data, then to read back the data, do:

1. Wait until IN ( 00 FDh ) bit 0 is 1 .
2. Read data from IN $(00 \mathrm{FCh})$.

To read the status of the printer, do an $\mathrm{IN}(01 \mathrm{FCh})$ twice in succession. If the values read don't match, repeat until they do. The bits in the byte returned are:

| Bit | Meaning if set |
| :---: | :---: |
| 7 | Printer failed |
| 6 | No printer |
| 5 | Ribbon present |
| 4 | Paper present |
| 3 | Cover down |
| 2 | Bail bar in |
| 1 | Controller failed |
| 0 | $?$ |

(The PCW9512 schematic shows printer signals for "SEL.HOM", "CAR.HOM", "SHIF" and "PSIF", but whether any of these corresponds to bit 0 (or indeed bits 7, 6 and 1 ) of this port is not known).

Daisywheel commands should be treated as big-endian words. The first 4 bits define the command; the remaining 12 bits are the parameter. If the first 4 bits are 0 , then the next 4 bits define a different type of command and the last 8 bits are the parameter.

| First byte |  | Second byte | Effect | Returns |
| :---: | :---: | :---: | :---: | :---: |
| High 4 bits | Low 4 bits |  |  |  |$\quad$| ribbon type |
| :---: |
| 0 |

### 6.3 PCW9512 PAR port

The PAR port is part of the PCW9512 printer controller, and is controlled by commands 2 (get status) and 4 (write byte to PAR).

The status byte gives the values of the following Centronics lines:

| Bit | Line |
| :---: | :---: |
| 7 | ACK |
| 6 | BUSY |
| 5 | ERROR |
| 4 | SELECT |
| 3 | PAPER OUT |
| 2 | Always 0? |
| 1 | Always 0? |
| 0 | Always 1? |

So to do output, wait until bit 6 goes to 0 and then write the data using command 4 .
Since the 9512 hardware supports the Centronics ACK signal, it is possible for a 9512 to act as the client computer in a LocoLink conversation - see section 7.3.

### 6.4 CPS8256 CEN port

The CPS8256 CEN port is at E3h.
To read its status, write 10 h to port E3h. Then read port E3h; bit 5 is set if the printer is ready.

To write data, write the character to port E8h. Then send the following bytes to port E3h: 5, E8h, 5, 68h. These will toggle the STROBE line.

### 6.5 Standalone CEN port

The standalone CEN port is at ports $84 \mathrm{~h}-87 \mathrm{~h}$.
The status is read from IN ( 84 h ). Bit 0 is 1 if the printer is busy, 0 if it's ready.
To write a byte, write it to port 87 h , then to port 85 h , then to port 87 h again. The two writes to port 87 h toggle the STROBE line.

## 7 Communications interfaces

### 7.1 CPS8256

The CPS8256 is based on a Z80-DART and an 8253 timer. Ports are as follows:

| Port | Meaning |
| :---: | :---: |
| E0 | DART Channel A data |
| E1 | DART Channel A control |
| E2 | DART Channel B data |
| E3 | DART Channel B control |
| E4 | 8253 counter 0 |
| E5 | 8253 counter 1 |
| E7 | 8253 write mode word |

To write a value to a DART register other than register 0 , send the register number and then the value to the "control" port (E1h or E3h). To read a register, send the register number to the control port and then do an IN on that port.

To read / write DART register 0, just read or write the value to port E1h or E3h. When writing, the bottom 3 bits of the value must be 0 ; otherwise one of the other regsters would be selected.

### 7.1.1 Z80-DART registers

The Z80-DART registers are numbered 0 to 5 . Many of the bits in these registers are not used by the CPS8256.

| Register | Bit | Meaning when read | Meaning when written |
| :---: | :---: | :---: | :---: |
| 0 | 0 | Receive character available | Must be 0 |
|  | 1 | Interrupt pending ${ }^{\text {A }}$ | Must be 0 |
|  | 2 | Transmit buffer empty | Must be 0 |
|  | 3 | DCD | Command |
|  | 4 | Ring Indicator | Command |
|  | 5 | CTS | Command |
|  | 6 | Not used | Not used |
|  | 7 | Break | Not used |
| 1 | 0 | All sent | Ext int enable |
|  | 1 | Not used | Transmit int enable |
|  | 2 | Not used | Status affects vector ${ }^{B}$ |
|  | 3 | Not used | Receive int mode |
|  | 4 | Parity error | Receive int mode |
|  | 5 | Receive overrun | Wait/Ready on R/T |
|  | 6 | Framing error | Wait/Ready function |
|  | 7 | Not used | Wait/Ready enable |
| 2 |  | Interrupt vector ${ }^{B}$ | Interrupt vector ${ }^{B}$ |
| 3 | 0 |  | Receive enable |
|  | 1-4 |  | Must be set to 0 |
|  | 5 |  | RTS/CTS set automatically |
|  | 6-7 |  | Receive bits (5,6,7,8) |
| 4 | 0 |  | Parity enabled |
|  | 1 |  | Parity even |
|  | 2-3 |  | Stop bits (1, 2, 3 for 1, 1.5, 2) |
|  | 4-5 |  | Not used |
|  | 6-7 |  | Clock multiplier(1,16,32,64) |
| 5 | 0 |  | Not used |
|  | 1 |  | RTS |
|  | 2 |  | Not used |
|  | 3 |  | Transmit enable |
|  | 4 |  | Send break |
|  | 5-6 |  | Transmit bits (5,6,7,8) |
|  | 7 |  | Not used |

${ }^{A}$ Only on channel A
${ }^{B}$ Only on channel B

### 7.1.2 CPS8256 Centronics port

The Centronics port (described in section 6.4) returns its status in register 0 of Channel B. The STROBE signal is controlled by bit 7 of register 5 (what the DART thinks is DTR) and the BUSY signal shows up in bit 5 (CTS) of register 0.

### 7.1.3 CPS8256 Serial port

The serial port is connected to Channel A of the DART.

- To check if the port can output, read register 0 of Channel A.
- If you are using software handshaking, check bit 2 (Transmit buffer empty) and wait until it's nonzero.
- If you are using hardware handshaking, check bit 5 (Clear to Send); when this goes to 1 , read register 1 until bit 0 (All Sent) is 1 .
- Then, to output, write the correct byte to the data channel.

To read from the port in non-interrupt mode:

- If hardware handshaking is enabled, check bit 0 of register 0 (RX character available) and if it's 0 , raise DTR (set bit 7 of register 5).
- Wait until bit 0 of register 0 becomes 1 .
- Read the character from the DART data channel.
- If hardware handshaking is in use, drop DTR.

To set transmit baud rate, send 36h to port E7h, and two bytes encoded rate to port E4h. To set the receive baud rate, send 76h to port E7h, and the two bytes to port E5h.

The encoded rate is $\frac{125000}{b a u d}$-send the high byte first, then the low byte.

### 7.2 SCA Mark 2 Interface

The SCA interface is programmed in the same way as the CPS8256, except that there's also a Real Time Clock fitted. The RTC is not emulated in JOYCE so this information has not been verified; use it at your own risk.

To read a byte from the RTC:

- Set channel A DTR.
- Reset channel B.
- For each bit: Unset channel A DTR, read the channel B Ring Indicator, and set channel A DTR. The bit obtained should be complemented. The first bit read is bit 7 of the byte; the last is bit 0 .

To write a byte to the RTC:

- Set channel A DTR.
- For each bit, if it's a 1 then reset channel B. If it's a zero set channel B RTS. Then reset and set channel A DTR.
- Finally, unset channel A DTR, reset channel B, read a single bit from the channel B Ring Indicator, and set channel A DTR again.

To send an RTC command:

- To start the command: Unset channel A DTR, reset channel B, set channel B RTS then set channel A DTR.
- Send the command bytes using the write code above.
- Read any result bytes using the read code above. For all result bytes except the last: Reset channel B, set channel B RTS, unset channel A DTR, set channel A DTR and then reset channel B again.
- Finally, set channel B RTS, set channel A DTR, unset channel A DTR and then reset channel B.

To read the clock:

- Send the command D0h, 0 .
- Send the command D1h; the next 4 bytes read will be hours, minutes, days, months (BCD).
- Send the command D0h, 5.
- The clock will return 3 bytes. The first is the year (BCD); I suspect the others are day and month again, which we ignore.

To write to the clock:

- Send the command D0h, 20h.
- Send the command D0h, hours, minutes, days, months (all BCD).
or:
- Send the command D0h, 5
- Send the command D0h, year, day, month (BCD).


### 7.3 LocoLink interface

LocoLink is used to connect the PCW to the parallel port of another computer. Usually this would be a PC, but it could also be a PcW16 and third-party software existed allowing a PCW9512 to do it (thus allowing transfers between 3" and 3.5" PCWs).

In early versions, the PC would act as a file server ("slave" in LocoLink terminology), and the PCW as the client (the "master"). A utility run on the PCW would transmit files to the PC. Later versions reversed the roles, with the PCW acting as the file server and the other computer treating it as one or more disc drives.

Although the LocoLink interface connects to the parallel port, it acts as a serial device, using only 4 wires (two each way). This is so that it can support non-bidirectional parallel ports.

On a PCW with the interface, the LocoLink appears at address 0FEh. The port behaves as follows:

| Bit | Input meaning | Output meaning |
| :---: | :---: | :---: |
| 0 | Data 0 | BUSY |
| 1 | Data 1 | ACK |

At the other end of the parallel cable, the two "Data" lines correspond to the first two data lines in the parallel port. BUSY and ACK correspond to the Centronics pins of the same name.

If a LocoLink interface is connected to both the expansion and parallel ports of a PCW9512, and bytes are sent to port 0 FEh, the bits in the parallel port change as follows:

| Value written |  | Value read |  |
| :---: | :---: | :---: | :---: |
| Bit 1 | Bit 0 | Bit 7 | Bit 6 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | 1 | 0 |
| 1 | 0 | 0 | 1 |
| 1 | 1 | 0 | 0 |

JOYCE v2.1.0+ can emulate the PCW end of a LocoLink connection.
The communications protocol used by the LocoLink interface is described in Appendix B.

### 7.4 PCW Linkit

The PCW Linkit interface is a similar device to the LocoLink (a 2-bit communication channel) except that both ends connect to PCW expansion ports. It appears at port 0 FFh. The values are carried by the two low bits of the port; the value read by one PCW is the binary inverse of the value written by the other PCW.

The communications protocol used is not known.

### 7.5 PCWMail

The PCWMail connection is a cable designed to be used in conjunction with the PCW's MAIL232 software to transfer files between two PCWs. Consequently, from the point of view of the PCWs it behaves like two CPS8256 interfaces connected back-to-back, with a null-modem cable in between.

### 7.6 Prototype serial interface

The original PCW specification mentions that the prototype PCW had a serial interface based on the Intersil IM6403 UART. Its data register was at address 0FEh for both input and output, and its status register at 0F9h (input only). JOYCE does not emulate this interface.

## 8 Floppy drives

The PCW floppy controller is the uPD765A, run in non-DMA mode. The FDC main status register is at I/O port 00 h ; its data register is at 01 h .

### 8.1 The floppy controller and other ports

The System Control port ( 0 F 8 h ) has five commands which affect the floppy controller:
02 If the floppy controller interrupts, the Z80 gets an NMI.
03 If the floppy controller interrupts, the Z80 gets a normal interrupt. If the Z80 has disabled interrupts, the interrupt line stays high until the Z 80 enables them again.

04 Floppy controller interrupts are ignored.
05 Set the floppy controller's "Terminal count", which aborts a data transfer.
06 Clear the floppy controller's terminal count.

### 8.2 Floppy drive support

PCW operating systems support two floppy drives, connected to the controller as drives 0 and 1.

On a PCW 8256, 8512 or 9512 , commands for drives 2 and 3 are sent to drives 0 and 1 (ie, the drive number is not completely decoded).

On a PCW 9256, 9512+ or 10, commands for drive 2 appear to go to drive 1 , except that the drive is always "ready", even when the motor isn't running. As far as I can see from the schematic, selecting drive 3 selects both drives simultaneously.

### 8.3 Floppy controller probe

Versions of LocoScript and CP/M written after the PCW9256 was released contain code to discover what sort of PCW is in use $-8256 / 8512 / 9512$ or $9256 / 9512+/ 10$. The code then detects whether $3.5^{\prime \prime}$ disc drives are in use.

The test is done in two stages.

### 8.3.1 Detect floppy controller type

1. Stop disc motors.
2. Send SENSE DRIVE STATUS for drive 0 to the disc controller until it reports drive 0 is not ready.
3. Send SENSE DRIVE STATUS for drive 2 . On an 8256 , 8512 or 9512 , this returns the same status as drive 0 (ie: not ready). But on a $9256,9512+$ or 10 , it returns a status of "ready".

### 8.3.2 Detect drive type

If a 9256-style controller was found, separate checks are then done on each drive to see whether they are 3.5 " or not. The test is performed once on drive 0 and once on drive 2. The test on drive 2 will return results that are valid for drive 1 , for some strange reason.

1. Start disc motors.
2. Recalibrate the drive (ie, move the head to track 0 ).
3. Send SENSE DRIVE STATUS to the drive.
4. If the "Track 0 " bit is not set:

- For drive 0: If the "read-only" bit is set, the drive is 3 ". Otherwise it is 3.5 ".
- For drive 2: The drive does not exist.

5. If the "Track 0 " bit is set:

- Turn off the disc motors, and wait for them to stop.
- Send SENSE DRIVE STATUS to the drive again. If "Track 0 " is set, the drive is 3 ". Otherwise it is 3.5 ".


## 9 Hard drives

JOYCE does not emulate real PCW hard drives, so this information is not verified.

### 9.1 Cirtech Gem

Physically, the Gem drive (at least the one I have) is a Seagate ST351A/X IDE drive, jumpered for XT mode. If the jumpers are set for AT mode it is possible to connect it to a modern PC and access the data at a sector level. Jumper settings for the ST351A/X can be found on Dell's website: [http://support.euro.dell.com/support/edocs/dta/18814/00000003.htm](http://support.euro.dell.com/support/edocs/dta/18814/00000003.htm).

In XTA mode the drive has four registers, mimicking an XT hard drive controller. On the PCW they can be found at ports 0 A 8 h to 0 ABh . The information below is adapted from the Interrupt List entry for ports $0320 \mathrm{~h}-0323 \mathrm{~h}$, which is where the registers appear on a PC. For full programming information, see the IBM PC technical reference, pages 1-187 to 1-201.
0A8h Data register.
0A9h When read: controller status. When written: Reset controller.
0AAh When read: controller DIP switches. When written: Generate controller-select pulse.

0ABh When written: DMA and interrupt mask (not used on the PCW)
In addition, the Gem interface has a 4 k boot ROM. It would appear that on initial startup, memory accesses with A7 reset go to the boot ROM, while memory accesses with A7 set go to the PCW mainboard. So the 4 k ROM is mapped into memory from $0000-007 \mathrm{~F}, 0100-017 \mathrm{~F}, 0200-027 \mathrm{~F}, \ldots, 1 \mathrm{~F} 00-1 \mathrm{~F} 7 \mathrm{~F}$.

The first thing the GEM boot rom does is to mimic the normal PCW boot process by copying the standard boot image (section 2 ) into memory. It does this by repeated memory reads (from address 80 h , so with A7 set) until the sequence D3 F8 [OUT $(0 \mathrm{~F} 8 \mathrm{~h}), \mathrm{A}]$ is encountered. Then it executes its own write to that port to switch to normal execution, and copies itself into RAM.

While the ROM is paged in, all I/O port accesses use 16-bit I/O [OUT (C),A style], with the top 8 bits of the address set to 80 h . The first instruction after the boot ROM has been copied into RAM is IN A,(0A9h), with A=0. Presumably this I/O read, with the top 8 bits of the address all 0 , pages the boot ROM out.

The format of the Gem drive boot track is documented in Appendix C.
In a Gem-2 (mirrored) configuration, the 'main' drive is drive 1 (ie, jumpered as slave) and the 'backup' drive is drive 0 (ie, jumpered as master).

### 9.1.1 Cirtech Gem (ATA)

I've also seen (but not really studied) a Gem drive based on a Conner Peripherals CP3024, which is ATA rather than XTA. The ATA registers would be mapped at 0A8h0AFh:

0A8h Data
0A9h Error / Features
0AAh Sector count
0ABh Sector number
0ACh Cylinder low
0ADh Cylinder high
0AEh Drive / Head
0AFh Status / Command
with the interface presumably converting between the 16-bit transfers expected by the drive, and the 8 -bit transfers done by the Z80.

### 9.1.2 Cirtech Insyder / Hardpak

These are pretty much Gem drives in different form factors (the Insyder is fitted inside a PCW9512, and the Hardpak includes a 2.5 " hard drive in the interface box). I have examined an Insyder, which again was an ATA drive. Before a transfer, the driver writes 0 to port 0 FF94h, which may be to prepare whatever mechanism converts between 8 -bit and 16 -bit transfers.

On the disk, sectors are stored with a non-obvious byte arrangement. Each 512-byte sector is stored as 256 little-endian words:

- The high bytes of words 0-127 give bytes 0-127 of the sector.
- The low bytes of words 0-127 give bytes 128-255 of the sector.
- The high bytes of words 128-255 give bytes 256-383 of the sector.
- The low bytes of words 128-255 give bytes 384-511 of the sector.


### 9.2 Cirtech Flash Drive

The Flash Drive is an adaptation of the Gem drive concept, except that both hard drive and boot ROM are replaced with one or two Intel E28F008SA flash chips. There is also a physical switch to disable booting from the Flash Drive, allowing the PCW to be booted as normal if the drive does not contain a valid boot image. In normal use the drive is read-only; special utilities are supplied to erase it and copy files to it.

The drive is paged in by a read from I/O port $0 x x D 8 h$, with the high byte of the address specifying which 32 k bank to select. This mechanism would allow a Flash Drive of up to 8 Mb . However the supplied utilities are only aware of the $1 \mathrm{Mb} / 2 \mathrm{Mb}$ configurations. Reading from I/O port $0 x x D 9 h$ pages the drive out again.

When the drive is paged in, the selected memory bank is visible at $00 \mathrm{~h}-7 \mathrm{Fh}, 0100 \mathrm{~h}-$ $017 \mathrm{Fh}, 0200 \mathrm{~h}-027 \mathrm{Fh} . . .0 \mathrm{FF} 00 \mathrm{~h}-0 \mathrm{FF} 7 \mathrm{Fh}$. Code that is accessing the drive, and any transfer buffers, must therefore be between addresses $0 \mathrm{xx} 80 \mathrm{~h}-0 \mathrm{xxFFh}$.

Because of the physical design of the interface, the data lines for the first chip are connected in reverse order (the Z80's bit 0 is the chip's bit 7). This doesn't matter for data reads and writes, but the supplied utilities have to cope with this when issuing commands and reading the status register. For example, to check the 'low voltage' indicator in the status register the utilities have to look at bit 5 for the first chip, bit 3 for the second.

If the 'autoboot' switch is turned on, then when the PCW is booted bank 0 of the drive is mapped into memory, and therefore should contain a valid boot program. As with the Gem drive, its first action is to read the standard boot image into memory, by repeated memory reads from 80 h . Similarly, port I/O is performed in 16 -bit style with the bit 15 of the port address set until the standard boot image has been read, and 8-bit style subsequently. On the Gem drive this would page out the boot ROM, but as the Flash drive does not have a separate boot ROM I suspect this may just be legacy code.

The format of the Flash drive boot track is documented in Appendix D.

### 9.3 ASD PCWHD10 / PCWHD20

I haven't seen one of these drives, so this information comes from disassembling the driver (ASD.FID). The drive uses an ATA interface, and appears to make 8-bit transfers. The registers are:

0A0h DataA
0A1h Error / Features
0A2h Sector count
0A3h Sector number
0A4h Cylinder low
0A5h Cylinder high
0A6h Drive / Head
0A7h Status / Command
The review in ' 8000 Plus' says that the ASD drive can have 1-6 partitions, but the driver I have doesn't support this.

### 9.4 Timatic Winchester Expansion Box

This is a 20 Mb Seagate ST225, connected to the PCW through a SASI interface. The controller appears to be something similar to an NCR 5380, mapped into PCW I/O space at ports 0A0h-0A7h:

0A0h SCSI data read/write
0A1h Initiator command register
0A2h Mode register

0A3h Target command register
0A4h SCSI bus status register / select register
0A5h Bus and status register
0A6h Start DMA target receive / Input data register (neither used by PCW)
0A7h Start DMA initiator receive / reset parity (neither used by PCW)
The format of the partition table is described in Appendix E.

### 9.5 Other hard drives

'8000 Plus' has also reviewed several other hard drives, for which I have no programming information:

ACC Hard Disc: No information available.
Vortex System 2000: A Miniscribe 8450 XT. I've seen this described as connected through a SCSI interface, but the 8450 XT drive uses XTA, not SCSI (though apparently some versions used the same 50-pin connector as SCSI drives). The same drive was sold for other systems, notably the Amiga, Atari ST and IBM PC, using an appropriate "personality module" to interface to the host computer.

Cirtech Diamond: An earlier version of the Gem, but based on a SCSI interface rather than IDE. Among its features was the ability to connect up to seven PCWs to a single drive, taking advantage of the ability of the SCSI bus to support multiple controllers.

## 10 Keyboard

The keyboard appears as a memory-mapped device at 3FF0h-3FFFh in memory block
3. The first 12 bytes give the status of pressed keys:

| Address | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 3FF0h | Keypad 2 | Keypad 3 | Keypad 6 | Keypad 9 | Paste | F1/F2 | Keypad 0 | F3/F4 |
| 3FF1h | Keypad 1 | Keypad 5 | Keypad 4 | Keypad 8 | Copy | Cut | PTR | Exit |
| 3FF2h | $[+]$ | $1 / 2$ | Shift (both) | Keypad 7 | $>$ | Return | $]$ | Del-> |
| 3FF3h | $\cdot$ | $?$ | $;$ | $<$ | P | $[$ | - | $=$ |
| 3FF4h | , | M | K | L | I | O | 9 | 0 |
| 3FF5h | Space | N | J | H | Y | U | 7 | 8 |
| 3FF6h | V | B | F | G | T | R | S | 6 |
| 3FF7h | X | C | D | S | W | E | 3 | 4 |
| 3FF8h | Z | Shift Lock | A | Tab | Q | Stop | 2 | 1 |
| 3FF9h | <-Del |  | J1: Fire 1 | J1: Fire 2 | J1: Right | J1: Left | J1:Down | J1:Up |
| 3FFAh | Alt | Keypad . | Keypad Enter | F7/F8 | [-] | Cancel | Extra | F5/F6 |
| 3FFBh |  |  | J2: Fire 1 | J2: Fire 2 | J2: Right | J2: Left | J2: Down | J2: Up |

Using the key numbering scheme in the PCW manual:

- Keys 0-71 correspond to bit $(\mathrm{n} \bmod 8)$ of byte $(\mathrm{n} / 8)$ of the map.
- Key 72 corresponds to bit 7 of byte 9 .
- Keys 73-80 correspond to bits 0-7 of byte 10 .

The entries marked J1 and J2 are for keyboard joysticks (see below).
The last four bytes contain controller status in bits 6 and 7. Bits $0-5$ of each byte are used (by analogy with the two joystick entries) to provide keyboard combinations that may be useful as joysticks.

| Address | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 3FFCh <br> (with LK2 present) | (KP Enter) <br> (Shift) | (Space) <br> (S) | (KP 0) <br> (D) | (Exit) <br> (A) | (F1/F2) <br> (X) | (F3/F4) <br> (W) |  |  |
| 3FFDh | $\sim$ LK2 | Shift Lock <br> LED | (Space) | (KP 2) | (KP 3) | (KP 1) | (KP .) | (KP 5) |
| 3FFEh | LK3 | LK1 | (Shift) | (Space) | W R P ] <br>  <br> 3F. $1 / 2$ | Q E O [ <br> L <, / | Z X C V <br> B N M | A S D F <br> G H J |
| 3FFh | Update <br> flag | Ticker | (Shift) | (Space) | W R P [ <br> S F X V | Q E O [ <br> A D Z C | B N M <br> ,$. / 1 / 2$ | H J K L <br> $;<>$ |

3FFCh gives an inverted T pattern centred on F1. If link LK2 is present, it will also respond to a W/A/D/X diamond, with S as Fire 1 and Shift as Fire 2.

3FFDh maps to the numeric keypad.
3FFDh bit 6 reports the state of the Shift Lock LED; 1 if lit, else 0.
3FFDh bit 7 is 0 if LK2 is present, 1 if not.
3FFEh maps ASDFGHJ to up, ZXCVBNM to down, QEO[L</, to left, WRP];>. $1 / 2$ to right, Space to Fire 1, Shift to Fire 2.

3FFEh bit 6 is 1 if LK1 is present, 0 if not. However, if LK1 is present the keyboard enters a self-test mode and transmits test patterns rather than these flags.

3FFEh bit 7 is 1 if LK3 is present, 0 if not.
3FFFh maps HJKL; <> to up, BNM,./1/2 to down, QEO[ADZC to left, WRP[SFXV to right, Space to Fire 1, Shift to Fire 2.

3FFFh bit 6 toggles with each update from the keyboard to the PCW.
3FFFh bit 7 is 1 if the keyboard is currently transmitting its state to the PCW, 0 if it is scanning its keys.

If no keyboard is present, all 16 bytes of the memory map are zero.

### 10.1 Keyboard matrix

The physical layout of the keyboard matrix is given in the service manual:

| Pin | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| P10 | Keypad 2 | Keypad 3 | Keypad 6 | Keypad 9 | Paste | F1/F2 | Keypad 0 | F3/F4 |
| P11 | Keypad 1 | Keypad 5 | Keypad 4 | Keypad 8 | Copy | Cut | PTR | Exit |
| P12 | $[+]$ | $1 / 2$ | Shift (both) | Keypad 7 | $>$ | Return | $]$ | Del-> |
| P13 | $\cdot$ | $?$ | $;$ | $<$ | P | $[$ | - | $=$ |
| P14 | , | M | K | L | I | O | 9 | 0 |
| P15 | Space | N | J | H | Y | U | 7 | 8 |
| P16 | V | B | F | G | T | R | S | 6 |
| P17 | X | C | D | S | W | E | 3 | 4 |
| P24 | Z | Shift Lock | A | Tab | Q | Stop | 2 | 1 |
| P25 | <-Del | Keypad . | Keypad Enter | F7/F8 | $[-]$ | Cancel | Extra | F5/F6 |
| P26 | Alt |  | J1: Fire 1 | J1: Fire 2 | J1: Right | J1: Left | J1: Down | J1: Up |
| P27 |  |  | J2: Fire 1 | J2: Fire 2 | J2: Right | J2: Left | J2: Down | J2: Up |

### 10.2 Keyboard Links

The keyboard has three option links. By default they are all disconnected.
LK1: If connected, puts the keyboard into a test mode in which it repeatedly sends various patterns of data to the PCW. The Shift Lock LED will be constantly lit (or, more accurately, blinking faster than you can see).

LK2: If connected, pressing Shift does not cancel Shift Lock. Also enables W/A/D/X joystick, and resets bit 7 of byte 3FFDh.

LK3: If connected, sets bit 7 of byte 3FFEh. Has no other effects.

### 10.3 Keyboard Joystick(s)

The key numbering scheme on the PCW exactly matches the memory map until the gap at key 72. It also exactly matches the keyboard matrix schematic in the PCW9512 service manual - until key 72 .

As shown above, the keyboard schematic has entries in its matrix table for one or two joysticks. (Existing PCWs have no provision for connecting a joystick to the keyboard, but the PC1512 does). This may have been how the joystick(s) on ANT were to have been implemented.

My guess is that in the original ANT design, the keyboard matrix and the table in memory matched. When the PCW keyboard was created, the membrane was redesigned to move the now-redundant joysticks to the end of the layout, and the keyboard controller microcode rewritten to swap bytes 9 and 10 (bits 0-6) so their positions in the memory map didn't change.

### 10.4 Physical connection



The pinout above shows the keyboard socket on the PCW, seen from the outside of the case. The voltages used for signalling appear to be less than TTL normal, though the PCW9512 (and probably the other models) can take signals at TTL levels without apparent harm.

### 10.4.1 Wire protocol

By default, the data and clock lines are high. To send a bit, the keyboard drives the data line low or high, pulls the clock line low, and then a little later returns them both to high. Exact timings are unknown, though the PCW motherboard seems happy to accept timings similar to those used by the PC1512 keyboard (set data, wait for $5 \mu \mathrm{~s}$, set clock, wait for $5 \mu \mathrm{~s}$, return both lines to high, wait for $40 \mu \mathrm{~s}$ ).

A keycode is 12 bits long, with the most significant bit first. The first four bits are the offset in the memory map $(0-0 \mathrm{Fh})$, and the last eight bits are the value to be placed into memory at that address. The PCW keyboard toggles the DATA line twice before sending each word, but the gate array at the PCW end doesn't seem to need this.

When transmitting its state, the controller sends a 17-keycode packet. The first word is byte 0 Fh , with the top bit set to 1 ; then bytes $0-0 \mathrm{Eh}$; then byte 0 Fh again, with the top bit set to 0 .

## 11 Pointing Devices

### 11.1 AMX Mouse

This mouse appears at ports $0 \mathrm{~A} 0 \mathrm{~h}-0 \mathrm{~A} 3 \mathrm{~h}$. The interface is built around an 8255 PPI :
$\mathbf{0 A 0 h}$ (port A) gives vertical movement - low nibble $=$ number of moves up, high = number of moves down

0A1h (port B) gives horizontal movement - low nibble $=$ number of moves right, high $=$ number of moves left

0A2h (port C)
Input: gives button state in bottom 3 bits. These are 0 if the button is pressed,
else 1. Bit 0 is the left button; Bit 1 is middle; Bit 2 is right.
Output: Stop Press writes 0FFh followed by 0, presumably to reset the counters.
0A3h (PPI mode). Stop Press writes 93h at startup (Basic I/O mode, ports A and B input, port C low 4 bits input, high 4 bits output).

If at startup the value read from port 0 A 2 h is 10 h , Stop Press switches to accessing the AMX mouse through ports 80h-83h. Possibly this is to detect an ASD hard drive and avoid a conflict.

### 11.2 Kempston Mouse

This mouse appears at ports 0D0h-0D4h:
0D0h gives X position, 0-255. The same value can also be read from 0D2h.
0D1h gives Y position, 0-255. The same value can also be read from 0D3h.
0D4h gives button state in bottom 2 bits. Zero if the button is pressed, else 1 . Bit 0 is left; bit 1 is right. Other bits are 1.

### 11.3 Keymouse

The Keymouse connects between the PCW and the keyboard. It uses the same mechanism as the keyboard to appear as a memory-mapped device, replacing four of the keyboard joystick bytes:

3FFBh Bits 6-0: horizontal movement counter. Bit 7: Middle mouse button pressed.
3FFCh Bits 7-6: high bits of vertical movement counter.
3FFDh Bits 4-0: low bits of vertical movement counter.
3FFEh Bit 7: Left button. Bit 6: Right button.

### 11.4 Electric Studio light pen

The lightpen appears at ports 0A6h and 0A7h. Its position is calculated using a 12-bit position counter and two flag bits:

| Port | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0A6h | Position: Low 8 bits |  |  |  |  |  |  |  |
| 0A7h | 0 | V. Retrace | H. Retrace | 0 | Position: High 4 bits |  |  |  | port 0 A 7 h and checking the result is not 0 FFh . NEWSDESK does a slightly different check, enabling the screen (OUT 0xF8, 0x07) and immediately checking that bits 6 and 7 of port 0A7h are zero.

The 12-bit position counter remains unchanged until the pen sensor is activated. When it is activated, the counter starts decrementing, and continues to decrement until the next horizontal retrace. Thus the vertical position of the pen is detected by manually counting the number of horizontal retraces before it is triggered; the horizontal position by reading the position counter.

An outline of the code in DDESP that reads the light pen position:

1. Wait for port 0 FDh bit 6 to go high (ie, if the printer is doing anything, wait for it to finish).
2. Disable interrupts.
3. Wait for vertical retrace to go high ( 2 successive reads of port 0 A 7 h have bit 6 set)
4. Save the initial 12-bit value of the position register.
5. Wait for vertical retrace to go low ( 2 successive reads of port 0A7h have bit 6 clear)
6. Wait for horizontal retrace (read of port 0A7h with bit 5 set, followed by read with bit 5 clear).
7. If vertical retrace is now high, finish.
8. If current position value differs from previous value, the sensor has been triggered. Record $\mathrm{X}=$ (previous position - current position), $\mathrm{Y}=$ current Y coordinate.
9. Increment Y .
10. Repeat steps 6-9 for 288 screen lines, or until vertical retrace goes high.
11. Re-enable interrupts.

This may produce more than one pair of coordinates; if so, the light pen position is taken to be their average.

## 12 Joysticks

### 12.1 Keyboard joystick(s)

These are described in section 10.3.

### 12.2 Kempston interface

The Kempston interface is visible at port 9Fh. It appears to have the same bit assignments as the Spectrum version of the interface:

Bits 7-5 Ignored.
Bit 41 if the fire button is pressed.
Bit 31 if the joystick is pushed down.
Bit 21 if the joystick is pushed up.
Bit 11 if the joystick is pushed left.
Bit 01 if the joystick is pushed right.

### 12.3 Spectravideo interface

The Spectravideo joystick interface appears at 0E0h (so it cannot be used at the same time as a CPS8256 interface). The values it returns are:

Bit 7 Always 0 . If nothing is present on this port, 1 is returned.
Bit 6 Ignored.
Bit 5 Ignored.
Bit 41 if the joystick is pushed to the right.
Bit 31 if the joystick is pushed up.
Bit 21 if the joystick is pushed to the left.
Bit 11 if the fire button is depressed.
Bit 01 if the joystick is pushed down.

### 12.4 Cascade (JoyceStick) interface

The Cascade joystick interface also appears at 0E0h. The 'Head over Heels' driver for this joystick doesn't work with a Spectravideo interface; it uses these bits:

Bit 70 if the fire button is pressed.
Bit 6 Ignored.
Bit 5 Ignored.
Bit 40 if the joystick is pushed up.
Bit 3 Ignored.
Bit 20 if the joystick is pushed down.
Bit 10 if the joystick is pushed to the right.
Bit 00 if the joystick is pushed to the left.

### 12.5 DKTronics interface

The DKTronics interface is a register on the DKTronics sound board's AY-3-8912 sound generator chip. To read it, write 0Eh to port 0AAh and then read port A9h. This is a bidirectional port, and can also be used for output.

Head Over Heels uses these bits of the value that it reads:
Bit 7 Ignored.
Bit 60 if the fire button is pressed.
Bit 50 if the joystick is pushed up.
Bit 40 if the joystick is pushed down.
Bit 30 if the joystick is pushed to the right.

Bit 20 if the joystick is pushed to the left.

## Bit 1 Ignored.

## Bit 0 Ignored.

The interface was supplied with a joystick driver DEFJOY.COM, which converted joystick movements into keypresses. This works by patching the running copy of CP/M to add code to the interrupt handler; every 16 interrupts, it checks the joystick position and injects the appropriate scancodes into the keyboard queue. Since DEFJOY.COM uses hardcoded addresses and memory areas within $\mathrm{CP} / \mathrm{M}$, it only works on PCW8000 CP/M with BIOS 1.4.

## 13 Sound Generators

### 13.1 DKTronics sound generator

According to posts on www.amstrad.es, if I read Google Translate aright, this interface is based on an AY-3-8912, accessed using the following ports:
A9 Read currently selected register
AA Select register
AB Write currently selected register
As mentioned above, the joystick port is register 0Eh.

## 14 Networking

### 14.1 Multilink

The Multilink system was a ring-topology peer-to-peer network designed by Nine Tiles Computer Systems. It supported a range of 8 -bit and 16 -bit computers, including the PCW as well as the Apricot PC and BBC Micro. It could be used to access networked hard drives, designated FileStore or AmStore.

To its host computer, a Multilink interface is designed to appear roughtly like an 8251 USART. It uses two I/O ports:
0A6h Control / status. On input:

| Bit | Meaning |
| :---: | :---: |
| 7 | Always 1 (8251 DSR) |
| $\mathbf{6 - 2}$ | Always 0 (8251 error flags) |
| 1 | Set if byte waiting to send to PCW |
| 0 | Set if ready to receive byte from PCW |

On output, write 48 h (ie, set the 8251 Break and Reset signals) to reset the card. Other bits should be 0 .
0A7h Data (read/write)
On power-up, if there is no network connection, the card will send the byte sequence 00909900 to the PCW. This signifies 'ring broken at current station'.

A full description of the character sequences used to control the card, and the meanings of the bytes it returns, are outside the scope of this document.

### 14.2 Amstrel

HM Systems produced a version of their Minstrel server for Amstrad networking. This was an S-100 system running TurboDOS, which combined the features of MP/M and CP/Net. PCWs could thus either use it as a CP/Net fileserver, or behave as dumb terminals to 8 -bit or 16 -bit programs running on the server. It is likely that PCW workstations would have been connected to the server by RS232, rather than with specialised networking hardware.

## 15 Scanners / Image Capture

JOYCE does not emulate scanners or other image capture devices, so this section is sketchy at best.

### 15.1 MasterScan

The MasterScan is an optical sensor which clips to the print head of the PCW dotmatrix printer. The user is instructed to remove the printer ribbon, and the MasterScan software then programs the printer to draw a vertical line in graphics mode with minimal line spacing. As the head goes to and fro, the sensor is polled to scan the image.

The sensor is read from port 0 DFh - the bottom bit is 0 for light, 1 for dark.
The user guide for 'The Desktop Publisher' by Database Software mentions a "Dart Scanner" which probably refers to the MasterScan, since it was sold by Dart Electronics.

### 15.2 ProScan

ProScan is a package comprising a Naksha hand scanner, an interface to connect it to the PCW, and software to drive it. The software can also use an Amstrad FX9000T / FX9000AT fax machine as the image capture device.

The interface is accessed on ports 0E9h-0EFh. Ports 0EAh-0EDh appear to select what image capture device is to be used:

0EAh Fax (FX1)
0EBh Fax (FX2)
0ECh Hand scanner
0EDh Unknown, but there is at least some support for it in the software; possibly a second type of hand scanner.

### 15.3 Digitisers

Video capture devices were made by Electric Studio and Rombo. I don't have any software or drivers for these, so can't give any detail on how they operated.

## A Dot matrix printer fonts

The PCW dot-matrix fonts are stored in three tables in Bank 2. The addresses and sizes of these tables differ from CP/M version to CP/M version; you can use LPT8FONT ${ }^{2}$ to discover where the fonts are for a given CP/M version. Known font addresses are:

| CP/M version | Font starts at |
| :---: | :---: |
| $1.1,1.2,1.4$ | 5 E 28 h |
| $1.12,1.14,1.15$ | 5 EBDh |

There are three consecutive tables of font data:

## A. 1 The character width table.

This is always 64 bytes long, and used for spacing the characters when proportional mode is selected. To get the width for character <n>, read byte ( $\langle\mathrm{n}\rangle / 2$ ); the high nibble will be for the even-numbered character $(0,2,4, \ldots)$ and the low nibble for the odd-numbered one ( $1,3,5, \ldots$ )

## A. 2 The NLQ font

The font starts with a table (the character offset table) containing 129 words. Each word has the following bitwise structure:

Bit 15: The character has a descender; print it on the bottom 8 pins rather than the top 8.

Bits 14-12: Space to put at the left of this character.
Bits 11-0: Offset of the specification of this character, from the start of the font.
The last entry gives the offset of the first byte after the font. This means that for any character, the size of its description can be found by taking offset(char+1) - offset(char). In the standard fonts, offset(128) also gives the offset of the start of the draft font from the start of the NLQ font.

After the character offset table is a pattern table. Each entry in it is two bytes long; the high byte is printed on the first pass, and the low byte on the second (or vice versa? The high byte is drawn slightly above the low one, anyway). The least significant bit corresponds to the top pin.

The length of the pattern table isn't that important, but in the standard fonts it can be deduced simply by subtracting 258 from the offset of character 0 .

After that we have the character descriptions. As mentioned above, for each character, its description is from offset(char) to offset(char+1). An entry is a stream of bytes. If the top bit is set, it means: Leave a blank column before printing this column. The values of the low 7 bits are:

00h-79h: Multiply by 2 to get an offset into the pattern table. Then take the two bytes at that offset for the first and second pass.

7Ah: The two bytes after this code are printed on the first and second pass.

[^1]7Bh-7Fh: Repeat the next pattern (byte - 79h) times, putting a blank column before the second and subsequent repetitions.

## A. 3 The draft font

As with the NLQ font, the draft font starts with a character offset table, in which every word is formed:

Bit 15: The character has a descender; print it on the bottom 8 pins rather than the top 8.

Bits 14-12: Space to put at the left of this character.
Bits 11-0: Offset of the specification of this character, from the start of the font.
The last entry gives the offset of the first byte after the font. Fonts can use memory up to and including 6BFFh.

After the character offset table is a pattern table. Each entry in it is a single byte, since draft mode only prints one pass. The least significant bit corresponds to the top pin.

The length of the pattern table isn't that important, but in the standard fonts it can be deduced simply by subtracting 258 from the offset of character 0 .

After that we have the character descriptions. As mentioned above, for each character, its description is from offset(char) to offset(char+1). An entry is a stream of bytes. If the top bit is set, it means: Leave a blank column before printing this column. The values of the low 7 bits are:

00h-79h: This is an offset into the pattern table. The bit pattern for the next column is the byte at that offset.

7Ah-7Fh: Repeat the next pattern (byte -78 h ) times, putting a blank column before the second and subsequent repetitions.
(note that unlike the NLQ print, there is no literal bitmap type).

## A. 4 Some worked examples

## A.4.1 NLQ: Character 0 (à) using BIOS 1.15

Looking in the NLQ table, the first 2 entries are 01F6h 0209h. The character bytes between those offsets ( $60 \mathrm{~F} 3 \mathrm{~h}-6106 \mathrm{~h}$ ) are (all values in hex):

| Byte(s) | First pattern | Second pattern |
| :---: | :---: | :---: |
| 2 E | 30 | 20 |
| 14 | 04 | 40 |
| 15 | 00 | 10 |
| 03 | 00 | 44 |
| 08 | 08 | 00 |
| 1 A | 00 | 45 |
| 08 | 08 | 00 |
| 7 A 0144 | 01 | 44 |
| 08 | 08 | 00 |
| 4 C | 00 | 46 |
| 08 | 08 | 00 |
| 36 | 20 | 04 |
| 20 | 08 | 40 |
| 0 A | 04 | 00 |
| $2 B$ | 38 | 38 |
| 02 | 00 | 40 |
| 82 | (gap) 00 | (gap) 40 |

Which gives us the following two patterns - one from the first set of bytes:

and one from the second:


If we take a row from the second pattern, then the first, and so on, then the letter appears:

```
..... .2............. .
. }
```



## A.4.2 Draft: Character 0 (à) using BIOS $\mathbf{1 . 1 5}$

In the draft table, the first two words are 0157 h 015 Ch . Adding these to the base of the font gives 6948 h and 694 Dh ; so the bytes between 6948 h and 694 Ch inclusive are the pattern for character 0 .

The bytes are: 050 E 97 C 79201 and these expand to:
05 -> patt[5] $=0 \times 20$
0E $->$ patt[14] $=0 \times 54$
97 -> patt[23] = 0x55, blank column first
C7 -> patt[71] $=0 \times 56$, blank column first
92 -> patt $[18]=0 \times 38$, blank column first
01 -> $\operatorname{patt}[1]=0 \times 40$
and, translated to a bitmap, these are:

```
255534
045680
...\#.....
. \#
.\# \# \# .
.\# \# \# \#.
\# \#.
. \# \# \#
```


## A.4.3 Repetition of columns: Character 62 (' $=$ ') using BIOS 1.4

This character is number 62 . So 124 bytes from the start of the offset table, we find the two words 02B3h, 02B5h. Thus we know the character description fits in 2 bytes, and starts 02B3h bytes from the start of the font.

The two bytes found there are:

## 7Dh [repeat 5 times]

0Ah [pattern]
Entry 0 Ah in the pattern table is 14 h , so the character is formed:

```
.........
# # # # #
# # # # #
-
.........
```

with the blank columns inserted automatically.

## A. 5 Matrix fonts in LocoScript 1.00-1.20

The fonts are stored in the file MATRIX.STD on the boot disc, in the same order as in CP/M. The data start at an offset of 011Ah from the start of the file.

LocoScript 1 is able to print 224 characters - numbers 0-127 and 160-255. These are stored as a single block of bitmaps in MATRIX.STD, which subtracts 32 from character codes above 160 to create its internal character index.

The design of MATRIX.STD as a separate file seems to imply that other dot-matrix fonts could be loaded in LocoScript 1. However the only alternative LS1 fonts I've seen (in Digita International's Supertype) simply patch the existing MATRIX.STD file.

Note that later versions of LocoScript 1 (v1.30+) use the same font format, but different file formats - see below.

## A.5.1 PS widths table

There are 224 characters rather than 128 , so the PS widths table is 112 bytes long.

## A.5.2 NLQ font

Since there are 224 characters, the offsets table is 225 words long. The offsets to characters start at 0 ; ie, what must be added is the address of the character description table, not the address of the font itself. The offset table is at 18 Ah in the file, and the character description table is at 442h. The character description bytes are almost the same as in CP/M, but the special values of the low 7 bits are slightly different:
00h-7Ah: Multiply by 2 to get an offset into the pattern table. Then take the two bytes at that offset for the first and second pass.

7Bh: The two bytes after this code are printed on the first and second pass.
7Ch-7Fh: Repeat the next pattern (byte -79 h ) times, putting a blank column before the second and subsequent repetitions.

## A.5.3 Draft font

The draft font is at offset 1181h in MATRIX.STD. Its offsets table is again 225 words long. As in CP/M, offsets are based on the font address (1181h).

## A.5.4 Z80 code

The first 11Ah bytes of MATRIX.STD are the Z80 code that generates font bitmaps. Again, this seems to suggest that alternative fonts were planned; the people designing the characters would have been able to use any code they liked to generate them. Very similar code is used under CP/M.

The entry point is at the beginning of MATRIX.STD, and takes the following parameters:

```
A = character
BC = address of this routine (MATRIX.STD must be prepared to be
        loaded anywhere in memory).
DE = address of a byte to which character width should be written.
```

On return, the registers should be:

```
A = character
BC = address of the code that generates the character bitmaps
PS width of character stored.
DE = 1 + entry DE.
HL corrupt.
All other registers and flags preserved.
```

The character bitmap generation code should then be called with:

```
A = character
BC = address of this routine
DE = address of 24-byte buffer in which to store the generated character bitmap.
H = OFFh for NLQ, else draft.
Bit O of L is O for pass 1, 1 for pass 2 (or vice versa?)
```

On return, the registers should be:

```
BC IX corrupt.
DE incremented by number of bytes written to the buffer.
All other registers and flags preserved.
```


## A. 6 Matrix fonts in LocoScript $\mathbf{v} 1.31$

The MATRIX.STD file in this version of LocoScript has a 128-byte header, so 80 h needs to be added to all offsets.

## A. 7 Matrix fonts in LocoScript v1.40-1.50

These versions of LocoScript doesn't have a MATRIX.STD file. Instead they have a PRINTER.JOY. The format of the data is the same, but 1D6Fh needs to be added to all offsets.

## A. 8 Matrix fonts in LocoScript 2-4

In LocoScript 2, the dot-matrix printer font is stored in MATRIX.PRI (in versions prior to 2.20) and in MATRIX. \#xx font files (in versions 2.12 and later).

There are three versions of these files:
1.1 LocoScript 2.00-2.11. Support for 480 characters. User-defined characters not supported.
2.1 LocoScript 2.12-2.19. Support for 480 characters. User-defined characters supported.
3.1 LocoScript 2.20+. Support for 512 characters. User-defined characters supported.

The format of the files is broadly similar; they start with a 128-byte header:

| Offset | Value | Notes |
| :---: | :---: | :---: |
| 00 h | 3 ASCII bytes | File Type: 'CHR' for a font, 'PRI' for the printer driver itself |
| 03 h | Byte | Major version, 1-3 |
| 04 h | Byte | Minor version, always 1 |
| 05 h | 90 ASCII bytes | Identity: 3 lines each of 30 ASCII bytes |
| 5 Fh | Word | Link number |
| 61 h | Word | 16-bit checksum of file excluding header |
| 63 h | Word | Length of file in 128-byte records, excluding header |
| 65 h | 12 ASCII bytes | Style name |
| 71 h | Byte | Style pitch |
| 72 h | Byte | Font type / flags |
| 73 h | 8 ASCII bytes | Driver |
| 7 Bh | Word | Offset to the font within this file |
| 7 Dh | Word | Options |
| 7 Fh | Byte | Header checksum |

The font type / flags byte is decoded as follows:
Bits 0-2: Font type. Possible values include:
1 PCW8000 dot-matrix
2 PCW9000 daisywheel
3 External printer (dot-matrix, daisywheel, inkjet etc.)
4 External 24-pin dot-matrix printer
Bit 3: Set for a font, clear for a printer driver.
Bit 4: Set for files containing a dot-matrix font supported by LocoChar (major version 2 or 3 ).

For a font file, the offset to the font is $0 x 80$ (ie, the font immediately follows the header). For a printer driver file, the driver comes first and the font further on.

Taking 0 as the start of the font, it has this format:

| Offset | Value | Notes |
| :---: | :---: | :---: |
| 0000 h | 12 ASCII bytes | Character set name |
| 000 Ch | 2 bytes | Unknown |
| 000 Eh | Byte | Bit 7 set if all bitmaps are uncompressed? |
| 000 Fh | Byte | Bit 6 set if screen characters have been redefined |
| 0010 h | 240 bytes | PS widths table for 480 characters. |
| 0100 h | 128 bytes | (v2+) 16 8x8 bitmaps for screen characters |
| 0180 h | 1922 bytes (v1/v2) <br> 2050 bytes (v3) | Index table: four bytes per character, plus <br> one extra word at the end |
|  | 124 bytes | NLQ character bitmaps (second pass) |
|  | 124 bytes | NLQ character bitmaps (first pass) |
|  | 124 bytes | Draft character bitmaps |
|  | Varies | Character pattern data |

Note that even in a v3 file (which defines 512 characters) there are only 480 entries in the PS widths table. Characters 256-287 are skipped.

The 4-byte index entry for each character is formed:
DW offset The top 3 bits of the offset give the meaning of the remaining 13:
Offset $>=\mathbf{0 E 0 0 0 h}$ This is an accented character. Bits 13-0 of the offset give the base character number. Bits 4-0 of the flags byte give the accent character number. For example, character 200 (â) is stored as 61 E0 126 B . Offset 0 E 061 h means the base character is 61 h ('a'). Flags 12 h mean the accent number is 2 (circumflex, character 3).
Offset 0C000h-0DFFFh This is a duplicate character. Bits 13-0 of the offset give the duplicate character. For example, character 352 (capital Alpha) is stored as 41 C 0 FF 57 . Offset 0C041h means the shape from character 41h (' $A^{\prime}$ ) is used.

Offset 08000h-0BFFFh This is an uncompressed character (normally this would apply only to user-defined characters). Bits 13-0 of the offset give the address of its bitmaps relative to the start of the index table. The bitmaps are a standard size: 11 bytes for draft, 48 for NLQ.

Offset 00000h-03FFFh This is a standard character. Bits 13-0 of the offset give the address of its bitmaps relative to the start of the index table. The low 4 bits of byte 3 ('extra') give length of the 'draft' bitmap, and the remainder is the 'NLQ' bitmap.

## DB flags

Bit 7: Character shifted down. Shifted-down characters are printed on the bottom 8 printer pins, rather than the top 8 ; intended for characters with descenders.
Bit 6: Shift character down when superimposing an accent.
Bit 5: Character design cannot be copied in LocoChar. Set on the large mathematical symbols (large Pi, large Sigma etc.) because they are drawn in two halves, top and bottom.

Bits 4-0: For an accented character (offset $>=0 \mathrm{E} 000 \mathrm{~h}$ ), the accent number. Otherwise:

Bit 4: When superimposing an accent, it replaces a dot (eg, on ' i ' or ' j '). Any non-blank line from the accent will completely replace the corresponding line from the character.
Bits 3-0: Proportional spacing columns minus 11
DB extra For a character where offset $>=0 \mathrm{C} 000 \mathrm{~h}$, the low 8 bits of the end of the previous character's bitmap. Otherwise:

Bits 7-5: Blank columns at left (NLQ mode)
Bit 4: Blank columns at left (draft mode)
Bits 3-0: Number of bytes in draft character shape
This code will compute the number of bytes in a character shape:

```
if (char[n].offset & 0x4000)
{
return 0; /* This character is a reference */
}
else if (char[n+1].offset & 0x4000)
{
/* Next character is a reference */
    unsigned offset2 = (char[n].offset & 0x1F00) | char[n+1].extra;
    if (offset2 < (char[n].offset & 0x1FFF)) offset2 += 0x100;
    length = offset2 - (char[n].offset & 0x1FFF);
}
else
{
/* Next character is not a reference */
length = (char[n+1].offset & 0x1FFF) - (char[n].offset & 0x1FFF);
}
```

For compressed characters, following the offset in the index table leads you to the draftmode pattern. 'extra' gives the length of the draft-mode pattern in bytes; add it to the offset to get the address of the NLQ pattern.

In the pattern, bit 7 of a byte is set if it should be preceded by a blank column. Bits 6-0 give a pattern number:

00h-7Bh Bitmap reference. The bitmaps begin immediately after the index table; I have called this address index_end.

NLQ (v1): There is a table of bitmaps at index_end, containing 124 words. Within each word, the high byte is for the first pass and the low byte is for the second pass.
NLQ (v2/v3): There are two sets of bitmaps, each containing 124 bytes. The bitmaps for the first pass are at index_end+7Ch and the bitmaps for the second pass are at index_end.
Draft: There is a single set of bitmaps, at index_end+0F8h.
In all the tables, within each bitmap byte bit 0 is the top pin and bit 7 is the bottom pin.

7Ch Literal (only found in NLQ patterns). Followed by two bytes giving the pin bitmaps for the second and first passes.

7Dh-7Fh Repeat. The following column is repeated value-79h times.
For uncompressed characters, following the offset in the index table leads you to 11 bytes giving the character bitmap for draft mode, followed by 48 defining it in NLQ mode.

The draft mode shape is 11 bytes. In each byte, bits $0-7$ give the pin bitmap (bit 0 is the top pin, bit 7 the bottom).

The NLQ mode shape is 24 words. In each word, the high 8 bits give the pin bitmap on the first pass, and the low 8 bits the pin bitmap on the second pass.

## B The LocoLink wire protocol

I have examined, or know of, the following versions of LocoLink:
1.03 / 1.04: Distributed with LocoScript PC 1.x. A file server (LLPC.EXE) is run on the PC, and a command-line client program on the PCW (LLPCW.COM) is used to send files to the PC. The connection can either be through the LocoLink hardware, or a serial port.
2.02: For use with LocoScript PC Easy and LocoScript Professional 2 Plus. The file server (LLINK202.EMS) is run on the PCW. The PCW then appears as a drive within the Disk Manager at the PC end. Serial support is dropped and the LocoLink hardware is required.
3.0 / LocoLink for Windows: This is mainly a file format conversion program, but it can also access the PCW through the LocoLink hardware. Although the hardware is the same, version 3 of the file server software is required at the PCW end. The main difference from version 2 is that version 2 shares a single drive and lets the user on the PCW choose which one is shared; version 3 shares all drives and the user on the PC chooses which to use within the LocoLink software.

LocoLink16: When importing a file using the "Import" menu option, a PcW16 can access a non-16 PCW through the LocoLink hardware. This uses very similar client code to LocoLink for Windows (to the extent that I suspect the code was ported from one platform to the other). When in use, the PcW16's "Import Document" screen gains checkboxes for "LocoLink (A/B)", allowing documents from either drive of the PCW to be read in. Again, this requires version 3 of the file server at the PCW end.

At the lowest level, the system for sending data through the LocoLink hardware seems to be the same in all known versions. The protocol appears to be symmetrical - ie, the server and the client go through the same steps to transmit a packet. However, it's easier to see what is going on at the PCW end, where the LocoLink interface presents the data directly to the CPU, than at the PC end where the parallel port interface gets slightly in the way - see section B.1.1.

## B. 1 Basic concepts

LocoLink works with two wires in each direction - each computer can control the values of two, and read the values of the other two. The values taken together form a two-bit number ( $0-3$ ) and it's most convenient to describe the protocol in these terms. For PCW - to - parallel communications, ACK is the high bit of the number and BUSY is the low bit.

## B.1.1 Bit mapping at the PC end

On a PC parallel port, these lines are swapped over (BUSY appears on bit 7 and ACK on bit 6). On the wire, the sense of both lines is inverted (it's 1 if the PCW is sending 0 , and vice versa). Then when the PC reads the parallel port, the BUSY signal is inverted again:

| On the PCW |  |  | On the wire |  | On the PC |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| PCW writes | Bit 1 | Bit 0 | BUSY | $\sim$ ACK | $\sim$ BUSY | $\sim$ ACK | PC reads |
| 0 | 0 | 0 | 1 | 1 | 0 | 1 | 040 h |
| 1 | 0 | 1 | 0 | 1 | 1 | 1 | 0 h |
| 2 | 1 | 0 | 1 | 0 | 0 | 0 | 00 h |
| 3 | 1 | 1 | 0 | 0 | 1 | 0 | 080 h |

Additionally, when output is being made, the STROBE line must be raised and then lowered; otherwise the LocoLink interface does not detect the changed values.

## B. 2 Link idle

When the link initially starts, the server sends 2 and the client sends 3 . In the protocol described below, this means that the server is listening for the first packet.

## B. 3 Sending

## B.3.1 Sending a byte

Note: Bytes must only be sent in packets - see below.

- Wait until the value sent by the other end goes from 3 to 1 .
- Send 2 or 3 , depending whether bit 7 of the byte is 1 or 0 .
- Wait until the value sent by the other end goes from 1 to 3 .
- Send 0 or 1 , depending whether bit 6 of the byte is 1 or 0 .
- Wait until the value sent by the other end goes from 3 to 1 .
- Send 2 or 3 , depending whether bit 5 of the byte is 1 or 0 .
- ... and so on until all the bits of the byte have been sent.


## B.3.2 Sending a packet

Before sending a packet the value sent by the other end should be 2. It may also be 3 ; if so, send 3 and wait for it to change to 2 .

- Send 0.
- Wait until the value received goes from 2 to 3 .
- Send 1.
- Send one byte: the packet type.
- Send one byte: number of following bytes (can be 0 for none).
- Send any following bytes.
- Send two bytes: the 16 -bit CRC of the packet.
- Wait until the value received goes from 3 to 1 .
- Send 3.
- Wait until the value received goes from 1 to 3 .
- Send 2.


## B. 4 Receiving

## B.4.1 Receiving a byte

Note: Bytes are only received as part of packets - see below.

- Wait until the value sent by the other end becomes 2 or 3 . The low bit of the value gives bit 7 of the byte being read.
- Send 3.
- Wait until the value sent becomes 0 or 1 . This gives bit 6 of the byte being read.
- Send 1.
- Wait until the value sent becomes 2 or 3 . This gives bit 5 of the byte being read.
- Send 3.
- ... and so on until all the bits have been read.


## B.4.2 Receiving a packet

To receive a packet:

- Wait until the value sent by the other end changes from 3 to 0 .
- Send 3.
- Wait until the value sent by the other end changes from 0 to 1 .
- Send 1.
- Receive two bytes (see above). The first is the packet type, and the second is the number of additional bytes that follow.
- Receive the additional bytes, if any.
- Receive the 2-byte CRC.
- Wait for the value sent by the other end to go from 0 or 1 (bit 0 of the last byte) to 3 .
- Send 3.
- Wait for the value sent by the other end to go from 3 to 2 .


## B. 5 Example

Here the client sends a packet to the server:

| Client value | Server value | Comment |
| :---: | :---: | :---: |
| 3 | 2 | Client not listening; Server listening |
| 0 | 2 | Client starts sending packet |
| 0 | 3 | Server acknowledges |
| 1 | 3 | Client ready to transmit bytes |
| 1 | 1 | Server ready to receive bytes |
| 2 | 1 | Bit 7 of first byte is 0 |
| 2 | 3 | Bit 7 acknowledged |
| 0 | 3 | Bit 6 of first byte is 0 |
| 0 | 1 | Bit 6 acknowledged |
| 3 | 1 | Bit 5 of first byte is 1 |
| 3 | 3 | Bit 5 acknowledged |
| ... skip a lot more bits like this ... |  |  |
| 1 | 3 | Bit 0 of last byte is 1 |
| 1 | 1 | Bit 0 acknowledged |
| 3 | 1 | End of packet (server deduces this from byte count) |
| 3 | 3 | End of packet acknowledged |
| 2 | 3 | Client listening; server not listening |

This would seem to imply that packets must strictly alternate, since at the end of a conversation the other computer is now the one listening.

## B. 6 Serial connection

In LocoLink v1.0x, it is also possible for packets to be sent and received over an RS232 serial interface. In this case the packets are sent at 9600 baud with one stop bit. The same packet format is used (type, length, data, checksum).

## B. 7 Startup sequence

The first packet exchange is a startup sequence.
In version 1.03 / 1.04, this is:

| Sender | Type | Length | Additional bytes |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Client | 07 h | 02 h | 43 h | 31 h |  |
| Server | 55 h | 01 h | 07 h |  |  |

In version 2.02 , this is:

| Sender | Type | Length | Additional bytes |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Client | 0 Bh | $02 \mathrm{~h}-20 \mathrm{~h}$ | 41 h | 31h | Client program name, optional |
| Server | C3h | $01 \mathrm{~h}-1 \mathrm{Fh}$ | 0 Bh | Server program name, optional |  |

In LocoLink for Windows and LocoLink PcW16, the initial exchange is:

| Sender | Type | Length | Additional bytes |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Client | 5 Ah | $02 \mathrm{~h}-20 \mathrm{~h}$ | 46 h | 31h | Client program name, optional |
| Server | 18 h | $01 \mathrm{~h}-1 \mathrm{Fh}$ | 5 Ah | Server program name, optional |  |

For versions 2.02 and later, the program name may or may not be present. The other bytes must be exactly as given, or a "link failed to start" error will occur.

## B. 8 While the link is running

The server now waits for a packet from the client, and reacts depending on what it receives. The packet types used vary depending on LocoLink version.

## B.8.1 LocoLink v1.03 / v1.04

The server supports the following packet types:
14h Disconnects the link and shuts down.
21h Check space for file. Packet contains a little-endian 32-bit value (file length), followed by the filename.

2Eh Create file. Packet contains a little-endian 32-bit value (file length), followed by the ASCIIZ filename.

3Bh Append data bytes to currently open file. Packet contains the bytes to append.
48h Close file. Packet contains a word (probably file CRC).
6Fh Create directory. Packet contains ASCIIZ path name.
7Ch Find first file. Packet contains directory search flag ( 0 to search for directory, 1 for file) followed by ASCIIZ filename.

It returns the following packet types:
55h Result. Two bytes follow. The first is the type of the packet it is replying to, the second is an error flag ( 0 if succeeded, other value if failed).

62h Invalid packet type received. No bytes follow.

## B.8.2 LocoLink v2.02

The server supports the following packet types:
22h Disconnects the link and shuts down.
39h DOS function call. This packet can be 1-15 bytes long. The data bytes in the packet are:

| Byte | Meaning |
| :---: | :---: |
| 0 | Function (AH) |
| 1 | Subfunction (AL) |
| $2-3$ | BX |
| $4-5$ | CX |
| $6-7$ | DX |

In theory longer versions of this packet might also contain SI, DI and BP. Most function calls don't need to pass parameters and so just send a 1-byte packet. For example, call 0Eh (log in drive) doesn't bother to send a drive number, since a LocoLink 2.x server computer provides only one disc drive.

95h Requested data (see 7Eh below)
0C3h Acknowledge data return (see 0ACh, 0DAh below)
It returns the following packet types:
50h Result. Packet length is $0-8$ bytes; its payload is the values for AX, BX, CX, DX (low byte first).

67h Error. Packet length is 2 bytes; the first is the DOS error number (see INT 21h function 59 h ) and the second is 0 .

7Eh Request data. Used where the corresponding DOS function would pass data using a pointer or DMA. The packet contains 2 bytes. The first byte is a code giving the source of the data, the second is the maximum data size. The client will reply to this with a packet of type 95 h containing the requested data. The source codes are:

11h Fixed length - copied from DX in original function call
36h Fixed length - copied from DTA
5Bh Fixed length - copied from SI in original function call
80h ASCIIZ (eg: filename) - copied from DX in original function call
0A5h ASCIIZ (eg: filename) - copied from SI in original function call
0CAh ASCIIZ (eg: filename) - copied from DI in original function call
0EFh Fixed length - copied from immediately after previous parameter
0ACh Return data. Used where the corresponding DOS function expects data to be passed to it by a pointer or DMA. The packet type is 0 ACh ; the first byte is the location code (as for 7 Eh , but only $11 \mathrm{~h}, 36 \mathrm{~h}, 5 \mathrm{Bh}$ and 0 EFh are supported), and the remainder contains the data. The client will reply to this with a 0 C 3 h packet, the first byte of which is 0 ACh .

0DAh Keep-Alive. Used when the server requires user intervention while servicing a call from the client (for example, it is displaying a "Drive not ready" error message). Expects the client to acknowledge with a 0C3h packet, the first byte of which is 0DAh. This stops the client timing out waiting for a response from the server.

Once the server has sent a "success" or "error" packet (50h or 67h) the client can send another command packet or hangup packet.

DOS function calls supported by LocoLink PCW 2.02 are:

| Function number | Meaning | Parameters in initial packet | Additional transfers |
| :---: | :---: | :---: | :---: |
| 0Dh | reset | none | none |
| 0Eh | login | none | none |
| 10h | close disc label | none | none |
| 11h | get disc label | none | Server returns disc label if found |
| 13h | delete disc label | none | none |
| 16h | create disc label | none | Client sends extended FCB for lab |
| 17h | rename disc label | none | Client sends extended FCB for rena |
| 36h | get free space | none | none |
| 39h | create directory | none | Client sends directory name |
| 3Ah | remove directory | none | Client sends directory name |
| 3Bh | set current directory | none | Client sends new directory (*3) |
| 3Ch | create file | CX=attributes | Client sends pathname (*2) |
| 3Dh | open file | AL=mode | Client sends pathname |
| 3Eh | close file | BX=handle |  |
| 3Fh | read file | BX=handle, $\mathrm{CX}=$ count | Server sends data read |
| 40h | write file | BX=handle, CX=count | Client sends data to write |
| 41h | erase file | none | Client sends pathname |
| 42h | set file pointer | AL=whence, $\mathrm{BX}=$ handle |  |
| 43h | get file attributes | AL=0 | Client sends pathname |
| 43h | set file attributes | $\mathrm{AL}=1, \mathrm{CX}=$ attributes | Client sends pathname |
| 44h | get device information | $\mathrm{AL}=0 \mathrm{BX}=0 \mathrm{CX}=0$ |  |
| 47h | get current directory | none | Server returns current directory (*) |
| 4Eh | find first file | AL $=$ search attribute (*4) | Client sends search path. <br> If successful server returns find file |
| 4Fh | find next file | none | none |
| 56h | rename file |  | Client sends old \& new pathname |
| 57h | get timestamp | AL $=0, \mathrm{BX}=$ file handle |  |
| 57h | set timestamp | $\mathrm{AL}=1, \mathrm{BX}=$ file handle |  |
| 5Bh | create file (atomic) | CX=attributes | Client sends filename |

## Notes:

*1 These functions always return error 5, "access denied", since under CP/M user areas cannot be created or destroyed.
*2 LocoLink v2.x expects all pathnames to be absolute, eg Z:LLETTERS\PENNY.LS2. The client must also ensure that passed file names are in upper case, as the server does not check or enforce this.
*3 The current directory set by function 3 Bh is returned by function 47 h but it does not affect operations in any other way since (as mentioned above) absolute paths need to be passed to all the other functions.
*4 The search attribute is passed in AL whereas in the original INT 21 h API it is passed in CX.
*5 Unlike 'find first file', the result of 'find next file' is returned in the result packet rather than as a separate transfer. It consists of one word (AX) followed by bytes $0 \times 12$ onward of the find file data (but without the terminating zero byte on the filename; the caller has to deduce this using the packet length).

## B.8.3 LocoLink for Windows / LocoLink 16

The client may send the following packet types:
05h Echo. Contains 0-32 bytes of additional data. The server returns a packet of type 18 h containing one more byte than was sent; the first byte returned is 05 h and the rest is the additional data.

6Dh Disconnects the link and shuts down.
80h DOS function call. This packet can be 1-15 bytes long. The data bytes in the packet are:

| Byte | Meaning |
| :---: | :---: |
| 0 | Function (AH) |
| 1 | Subfunction (AL) |
| $2-3$ | BX |
| $4-5$ | CX |
| $6-7$ | DX |

Note that these packets may be larger than the equivalent packets sent by LocoLink v2.02. For example, function 0 Eh ( $\log$ in drive) now passes a drive number, since this version of LocoLink allows the host PC to switch between the PCW's drives.

0CCh In response to a packet of type 0B9h. The packet contains the requested data.
The server may send the following packet types:
18h Acknowledgement. Sent in response to a packet of type 05h, 2Bh, 0DFh or 0F2h. The first byte is the type of the packet it is acknowledging. For type 05h there are 1-20 For type 0F2h there is a second byte of data.

2Bh Keep-Alive. The client acknowledges with a type 18h packet.
93h End of DOS function call (success). Contains two bytes: the value returned by the function in AX .

A6h End of DOS function call (failure). Contains two bytes: the DOS error code.
0B9h Server requests data from client. Contains two bytes: the first byte is a code giving the source of the data, the second is the maximum data size. The client returns the data in a type 0 CCh packet. The source codes are:

11h Fixed length - copied from DX in original function call

36h Fixed length - copied from DTA
5Bh Fixed length - copied from SI in original function call
80h ASCIIZ (eg: filename) - copied from DX in original function call
0A5h ASCIIZ (eg: filename) - copied from SI in original function call
0CAh ASCIIZ (eg: filename) - copied from DI in original function call
0EFh Fixed length - copied from immediately after previous parameter
0DFh Data transfer from server to client. The first byte gives the destination of the data (using the same codes as 0 B 9 h ), the remainder of the packet is the data. Client acknowledges with a type 18 h packet.

0F2h Keep-alive? Appears to include one byte of data.
Version 3 of the LocoLink server on the PCW supports the same range of DOS function calls as version 2. However LocoLink for Windows and LocoLink 16 only use functions marked + . The other functions are present but may not be thoroughly debugged (for example, trying to get or set the volume label in LocoLink 3.00 always appears to fail with a 'drive not ready' error).

| Function number | Meaning | Parameters in initial packet | Additional tra |
| :---: | :---: | :---: | :---: |
| 0Dh+ | reset | $\overline{\mathrm{AL}}=\text { drive type DL = drive }$ <br> AL is 0 for CP/M, 0FFh for LocoScript | none |
| 0Eh+ | login | DL = drive | none |
| 10h | close disc label | none | none |
| 11h | get disc label | none | Server returns disc la |
| 13h | delete disc label | none | none |
| 16h | create disc label | none | Client sends extended |
| 17h | rename disc label | none | Client sends extended F |
| 36h | get free space | none | none |
| 39h | create directory | none | Client sends direct |
| 3Ah | remove directory | none | Client sends direct |
| 3Bh | set current directory | none | Client sends new |
| $3 \mathrm{Ch}+$ | create file | CX = attributes | Client sends pathn |
| 3Dh+ | open file | AL $=$ access mode $\mathrm{CL}=0$ | Client sends pat |
| 3Eh+ | close file | BX = handle | none |
| 3Fh+ | read file | $\mathrm{BX}=$ handle, $\mathrm{CX}=$ count of bytes | Server sends requ |
| 40h+ | write file | BX = handle, CX = count of bytes | Client sends |
| 41h | erase file | none | Client sends pa |
| 42h | set file pointer | AL=whence, $\mathrm{BX}=$ handle |  |
| 43h | get file attributes | AL=0 | Client sends pa |
| 43h | set file attributes | AL=1, $\mathrm{CX}=$ attributes | Client sends pa |
| 44h | get device information | $\mathrm{AL}=0 \mathrm{BX}=0 \mathrm{CX}=0$ |  |
| 47h | get current directory | none | Server returns current |
| 4Eh+ | find first file | CX = search attribute | Client sends sear <br> If successful server retur |
| 4Fh+ | find next file | Possibly last find file data (*5) | none |
| 56h | rename file |  | Client sends old \& ne |
| 57h | get timestamp | $\mathrm{AL}=0, \mathrm{BX}=$ file handle |  |
| 57h | set timestamp | $\mathrm{AL}=1, \mathrm{BX}=$ file handle |  |
| 5Bh | create file (atomic) | CX=attributes | Client sends fil |
| 68h | Flush file | BX = file handle |  |

## Notes:

*1 On LocoLink 3.00, attempts to get or change the drive label fail with a 'drive not ready' error. This is because the server requests the first 7 bytes of the extended FCB, but should request 8 (the eighth is the drive number).
*2 These functions always return error 5, "access denied", since under CP/M user areas cannot be created or destroyed.
*3 The current directory set by function 3Bh is returned by function 47h but it does not affect operations in any other way since (as mentioned above) absolute paths need to be passed to all the other functions.
*4 LocoLink v3.x expects all pathnames to be absolute, eg A:\USER.02\PENNY.LS2.
*5 The 'find next file' packet may either contain 1 byte (4Fh) or 17 bytes (4Fh, followed by bytes $0 \times 06-0 \times 15$ from the find file data of the last file found). This is to allow depth-first search of directories; if LocoLink encounters a subdirectory,
it will commence a new search to list files within that subdirectory. Once it has finished it will then send the long version of the find-next packet to resume the original search of the root directory where it left off. Bytes 0x06-0x14 of the find file data therefore need to contain enough information to identify which search is being continued.
*6 Unlike 'find first file', the result of 'find next file' is returned in the result packet rather than as a separate transfer. It consists of bytes $0 \times 11$ onward of the find file data (but without the terminating zero byte on the filename; the caller has to deduce this using the packet length).

## B. 9 Emulated DOS filesystems

LocoLink 2.x and LocoLink for Windows / LocoLink 16 both present the PCW's CP/M filesystem as a DOS directory tree. How this is done depends on the selected display mode, LocoScript or CP/M. In LocoLink 2.x, this is set on the PCW. In LocoLink for Windows / PcW16, LocoScript or CP/M mode is selected on the PC and passed as a parameter to the 'reset disks' function.

- In LocoScript mode, the root directory of the filesystem is empty, except for subdirectories corresponding to the eight LocoScript groups. The subdirectory names will be taken from the group names (so EXAMPLE.GRP would become a subdirectory called EXAMPLE), or GROUP.n if there is no .GRP file.
- In CP/M mode, user 0 becomes the root directory, and there will be up to 15 subdirectories named USER. 01 to USER. 15 .

In LocoLink 2.x, there is also an option to hide empty user areas, which is selected by default.

LocoLink 2.x, which supports only one drive, appears to use $\mathrm{Z}: \backslash$ as the drive letter in absolute path names. LocoLink 16 uses $\mathrm{A}: \backslash$ (and presumably $\mathrm{B}: \backslash$ for the second drive, if one is present)

## C The Gem Drive System Track

The first track of the Gem drive contains a boot image, which is loaded and executed by the 4 k boot ROM. The hard drive setup program provided with the drive will write this when asked to repartition the drive or update the boot loader. On the utilities diskette it is stored in a file called HD.SYS

The boot image starts with a header, corresponding to the MBR on an IBM-formatted hard drive:

| Offset | Size | Description |
| :---: | :---: | :---: |
| 0 | Word | Offset to boot programs table |
| 2 | Word | Offset to image of HDRIVER.FID |
| 4 | Word | Offset to the splash screen |
| 6 | Word | Total length of boot image |
| 8 | Byte | Options byte |
| 9 | 17 bytes | CP/M Plus DPB (used for all partitions) |
| 1 Ah | Byte | Sectors per track |
| 1 Bh | Word | First cylinder of partition 1 |
| 1 Dh | Word | First cylinder of partition 2 |
| 1 Fh | Word | First cylinder of partition 3, 0 if none |
| 21 h | Word | First cylinder of partition 4, 0 if none |
| 23 h | Byte | 8-bit checksum of bytes 0-22h |

Note that the SPT field in the DPB at offset 9 gives sectors per cylinder, while the 'Sectors per track' at offset 1Ah really does give sectors per track. For example, a Gem drive with 5 heads and 17 sectors would have $\mathrm{SPT}=5 * 17=85$, while the field at offset 1 Ah would hold 17.

Three bits of the options byte are used:
Bit 7 Set to load CP/M by default, clear to load LocoScript by default. Hold the ALT key when booting to load the other OS.

Bit 4 Set if this is a Gem-2 (mirrorred) system. In this configuration, sectors are read from drive 1 (the main drive) and written to both drive 1 (the main drive) and drive 0 (the backup drive). Hold the B key when booting to disable mirroring and boot from the backup drive.

Bit 0 Set if a splash screen is present
Working through the fields in order:

## C. 1 The boot programs table

This table contains a list of boot programs. Each entry is five bytes long:

| Offset | Size | Meaning |
| :---: | :---: | :---: |
| 0 | Byte | 8-bit checksum of the first 512 bytes of the EMS/EMT file |
| 1 | Word | Offset of boot program from start of table |
| 3 | Word | Length of boot program |

The end of the table is indicated by a boot program with offset 0 . If the checksum of the first 512 bytes of the EMS/EMT file does not match any of the entries in the table, the boot ROM will give a single beep and refuse to execute it.

If a matching boot program is found, it will be copied to 0D000h and run with the following parameters:

- HL = length of HDRIVER.FID. HDRIVER.FID will be in memory at 0D000h + length of boot program.
- $\mathrm{C}=$ boot program number (1-based).
- The selected EMS / EMT file will be in memory from 0000h up.

The task of the boot program is to inject the HDRIVER.FID image into the loaded EMS / EMT file, so that it boots from the hard drive rather than the floppy. The version of the bootloader that I have studied can do this to six variants of the CP/M EMS file, and 64 variants of the LocoScript EMS file.

## C. 2 The HDRIVER.FID image

This is an exact copy of the HDRIVER.FID used to access the hard drive when booting from floppy.

## C. 3 The splash screen

This is a $720 \times 146$ bitmap. It is stored as 19 rows, each containing $908 x 8$ character cells. The first row should be blank, because it is used to draw the 55 scanlines above and below the picture.

## C. 4 HDRIVER.FIC image

One Insyder drive that I have examined stored a second driver after the splash screen. This was used when booting LocoScript 3.06+, with the original driver used by CP/M.

## D The Flash Drive System Track

The Cirtech Flash drive begins with a boot image, which is executed by the PCW at startup if the 'Autostart' switch is on. The INSTALL program provided with the drive writes this boot image when initialising the drive. On the utilities diskette it is stored in a file called FD.SYS.

The file / boot image begins with a header:

| Offset | Size | Description |
| :---: | :---: | :---: |
| 0 | Word | Short jump to boot code at 001Fh |
| 2 | Word | Offset to boot programs table (as for Gem drive) |
| 4 | Word | Offset to image of FDRIVER.FID |
| 6 | Word | Offset to the splash screen |
| 8 | Word | Offset to image of FDRIVER.FIC |
| 0 Ah | Byte | Default operating system. Bit 7 set for CP/M, reset for LocoScript |
| 0 Bh | 17 bytes | CP/M Plus DPB for the drive |
| 1 Ch | Word | Sector number of first sector of directory |
| 1 Eh | Byte | Checksum |
| 1 Fh | 3 bytes | Jump to first stage boot code at 0100h |

Note that the first-stage boot code is stored in FD.SYS at 0080h, but will be mapped into memory at 0100 h at boot time.

The remaining contents of the boot image (boot programs table, driver .FID file, splash screen, .FIC file) are similar to their Gem Drive counterparts.

## E The Timatic Winchester Expansion Box Partition Table

The driver that I have seen Winchester Expansion Box assumes a 20 Mb drive, with the partition table at logical sector 0xA28F.

At offset 1 Dh in the sector is a printable list of drives, six bytes per drive. Each entry reads "\#:nnM," with the last being "\#:nnM." followed by CR / LF / LF / 0FFh. The driver will use this as a template for its startup message, replacing the '\#' entries with the drive letters in use.

At offset 64 h in the sector is a table of CP/M DPBs, 17 bytes per drive. These all report 4 128-byte sectors per track (that is, a single 512-byte sector per track) so the CP/M track number corresponds to the SASI sector number. This would only work on a drive size up to 32 Mb . Following the last DPB is a 0 FFh byte.

Byte 255 of the sector is set when written to the XOR of the previous 255 bytes, complemented. Thus when the first 256 bytes of the sector are XORed together, the result should be 0 FFh .

Unused bytes in the sector are filled with the repeated text "C TURVEY."


[^0]:    ${ }^{1}$ Arnold Number Two

[^1]:    ${ }^{2}$ [http://www.seasip.info/Cpm/software/amstrad.html](http://www.seasip.info/Cpm/software/amstrad.html)

